

Modelling, Viewing, and Projection

8 March 2007

CMPT370

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Review last time

■ Rotations in 3D

- Euler angles, **gimbal** lock problem
- Virtual **trackball**
 - ◆ 2D **mouse** coords \rightarrow pt on **hemisphere**
- **Axis-angle** representation

■ Quaternions

- **Converting** from axis-angle to quaternion
- Using quaternions for **rotations**
- Constructing a **4x4** rotation matrix
 - ◆ GameDev article on quaternions

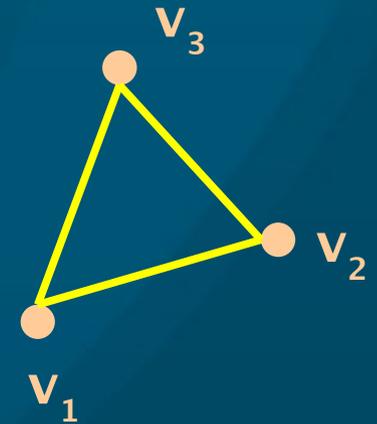
Outline for today

- **Modelling**: vertex lists, face lists, edge lists
 - OpenGL **vertex arrays**
 - OpenGL **display lists** (see RedBook ch7)
- **Viewing**: (see RedBook ch3)
 - Positioning the camera: **model-view** matrix
 - Selecting a lens: **projection** matrix
 - Clipping: setting the **view volume**
 - ◆ See UC-Davis ECS175 graphics course

Modelling polygons

- Simple **representation** (see CubeView):

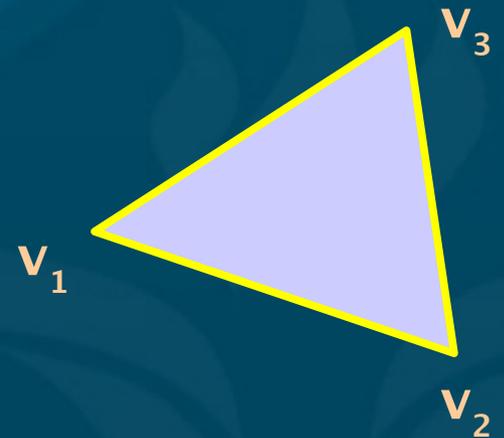
```
glBegin( GL_POLYGON );  
    glVertex3f( 0.0, 0.0, 0.0 );  
    glVertex3f( 1.0, 1.5, 2.2 );  
    glVertex3f( -2.3, 1.5, 0.0 );  
glEnd();
```



- **Problems**: inefficient, unstructured
 - What if we want to **move** a vertex to a new location?

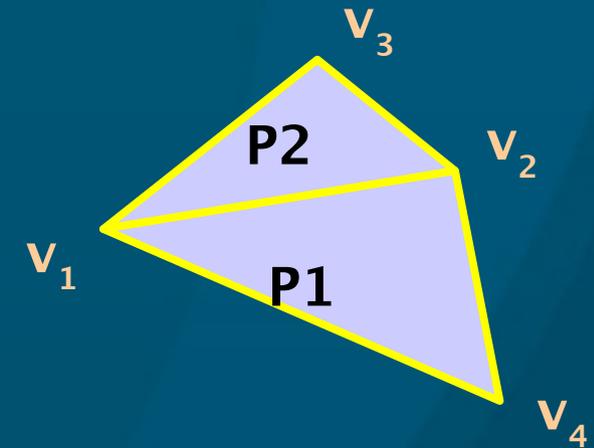
Inward/outward facing polygons

- The **normal** vector for a polygon follows the **right-hand** rule
- Specifying vertices in order (v_1, v_2, v_3) is **same** as (v_2, v_3, v_1) but **different** from (v_1, v_3, v_2)
- When constructing a closed surface, make sure all your polygons face **outward**
- **Backface** culling may mean inward-facing polygons don't get rendered



Vertex lists and face lists

- Separate **geometry** from **topology**
 - **Vertex** coords are geometry
 - Connections between vertices (**edges**, **polygons**) are topology



- **Vertex list:**

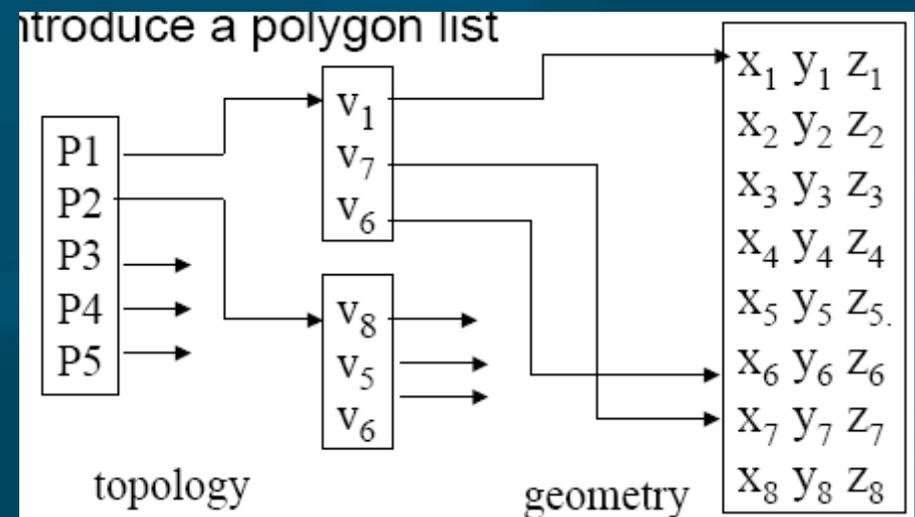
- ◆ $v_1 = \{x_1, y_1, z_1\}$

- ◆ $v_2 = \{x_2, y_2, z_2\}$

- **Polygon/face list:**

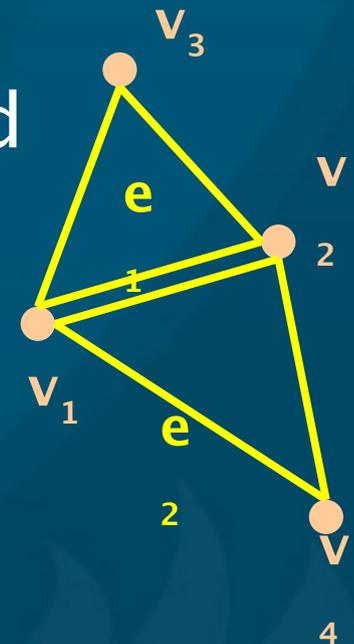
- ◆ $P_1 = \{v_1, v_2, v_3\}$

- ◆ $P_2 = \{v_1, v_4, v_2\}$



Edge lists

- If only drawing **edges** (wireframe):
 - Many **shared** edges may be duplicated
 - Similar to **face** list but for edges:
 - ◆ Does not represent the **polygons**!



- **Vertex list:**

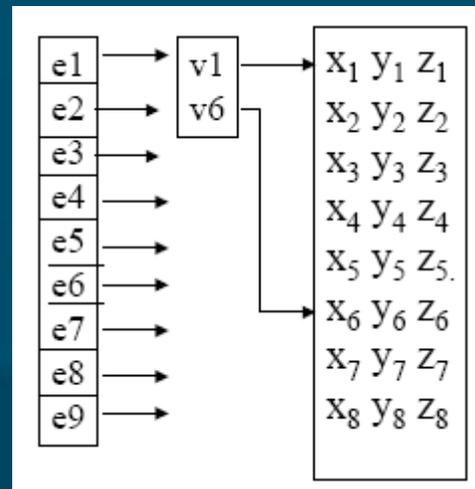
- ◆ $v_1 = \{x_1, y_1, z_1\}$

- ◆ $v_2 = \{x_2, y_2, z_2\}$

- **Edge list:**

- ◆ $e_1 = \{v_1, v_2\}$

- ◆ $e_2 = \{v_1, v_4\}$



OpenGL vertex arrays

- **Stores** a vertex list in the graphics hardware
 - ◆ Six **types** of arrays: **vertices**, colours, colour indices, normals, texture coords, edge flags
- Our vertex list in **C**:
 - ◆ `GLfloat verts[][3] = {{0.0, 0.0, 0.0}, {0.1, 0.0, 0.0}, ...}`
- Load into **hardware**:
 - ◆ `glEnableClientState(GL_VERTEX_ARRAY);`
 - ◆ `glVertexPointer(3, GL_FLOAT, 0, verts);`
 - **3**: 3D vertices
 - **GL_FLOAT**: array is of `GLfloat`-s
 - **0**: contiguous data
 - **verts**: pointer to data

Using OpenGL vertex arrays

- Use `glDrawElements` instead of `glVertex`
- Polygon list references **indices** in the stored vertex array
 - ◆ `GLubyte cubeIndices[24] = {0,3,2,1, 2,3,7,6, 0,4,7,3, 1,2,6,5, 4,5,6,7, 0,1,5,4};`
 - ◆ Each group of **four** indices is one quad
- Draw a whole object in **one** function call:
 - ◆ `glDrawElements(GL_QUADS, 24, GL_UNSIGNED_BYTE, cubeIndices);`

OpenGL display lists

- Take a **group** of OpenGL commands (e.g., defining an object) and **store** in hardware
- Can change OpenGL **state**, camera view, other objects, etc. without **redefining** this stored object
- **Creating** a display list:
 - ◆ `GLuint cubeDL = glGenLists(1);`
 - ◆ `glNewList(cubeDL, GL_COMPILE);`
 - `glBegin();; glEnd();`
 - ◆ `glEndList();`
- **Using** a stored display list:
 - ◆ `glCallList(cubeDL);`

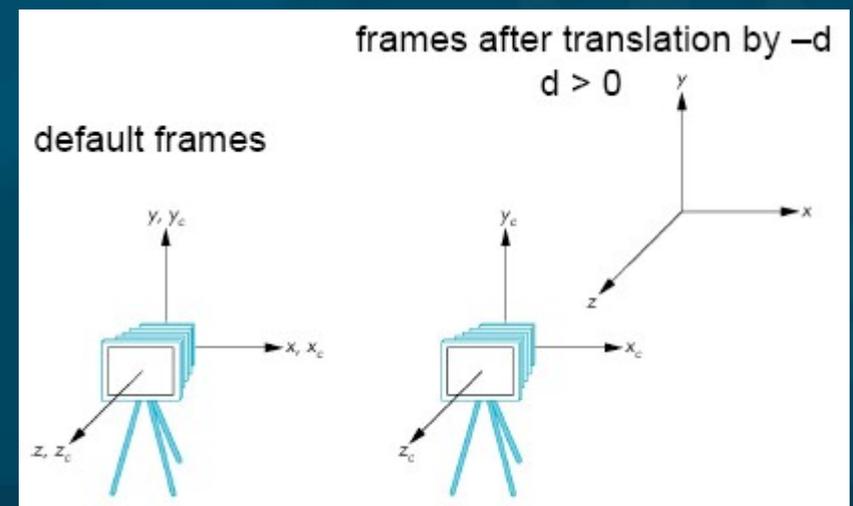
See RedBook ch7

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Positioning the camera: model-view

- The **model-view** matrix describes where the **world** is relative to the **camera**
 - Initially **identity** matrix: camera is at **center** of world, facing in **negative z** direction
- Say we want to **see** an object placed at the origin:
 - Move the **camera** in the **+z** direction, or
 - Move the **world** frame in the **-z** direction
 - Both are equivalent:
`glTranslatef(0., 0., -d);`

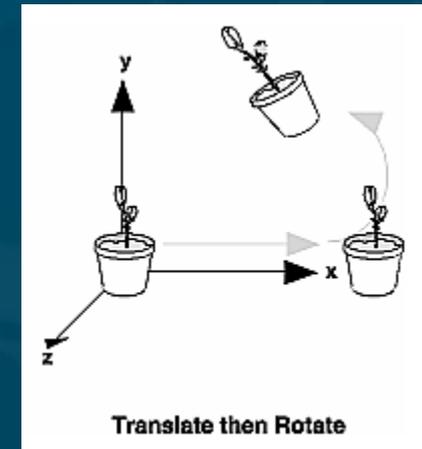


Order of transformations

- ◆ **C**: current **model-view** matrix
 - ◆ **M**: new additional **transformation**, via `glMultMatrix`, `glTranslate`, `glRotate`, etc.
 - ◆ **v**: vertex to be transformed
- OpenGL applies transforms in the order: **CMv**
 - So the **last** transform is applied **first!**

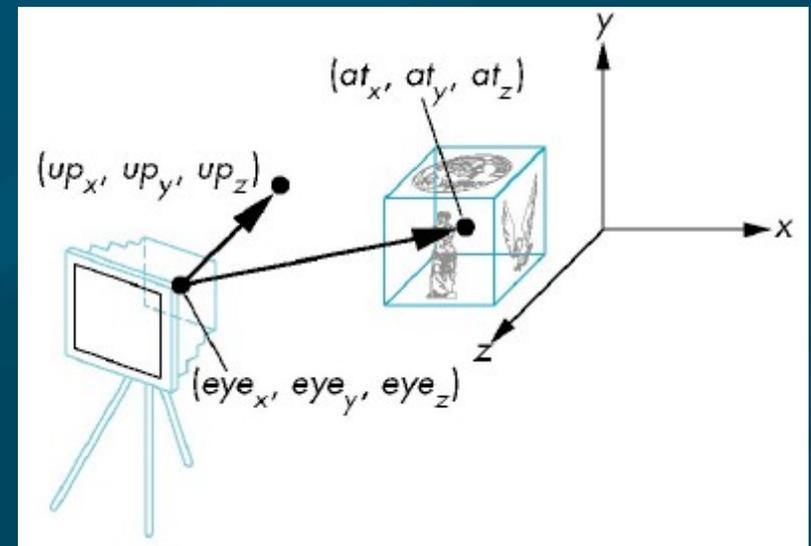
- ◆ `glMatrixMode(GL_MODELVIEW);`
- ◆ `glLoadIdentity();`
- ◆ `glRotatef(60., 0., 0., 1.);`
- ◆ `glTranslatef(10., 0., 0.);`
- ◆ `glBegin(GL_POINTS);`

- `glVertex3fv(vert);`



gluLookAt

- Handy **helper** function for setting up **model-view**
 - ◆ `#include <GLU.h>`
- Specify **eye** coords, where you want to **look at**, and direction of “**up**” vector:
 - ◆ `glMatrixMode(GL_MODELVIEW);`
 - ◆ `glLoadIdentity();`
 - ◆ `gluLookAt(eye_x, eye_y, eye_z, at_x, at_y, at_z, up_x, up_y, up_z);`



Selecting a lens: Projection

- The **projection matrix** maps **3D** points in the camera's frame to **2D** points on the image plane
 - **Input** to projection matrix is homogeneous coords **after** model-view matrix is applied
 - After multiplying by projection matrix,
 - ◆ **Divide** to ensure **homogeneous** coords: $[x \ y \ z \ 1]$
 - ◆ Take just the (x, y) coords as coords on image plane
 - **Default** projection matrix is the identity
 - ◆ **Orthographic** projection onto the xy plane

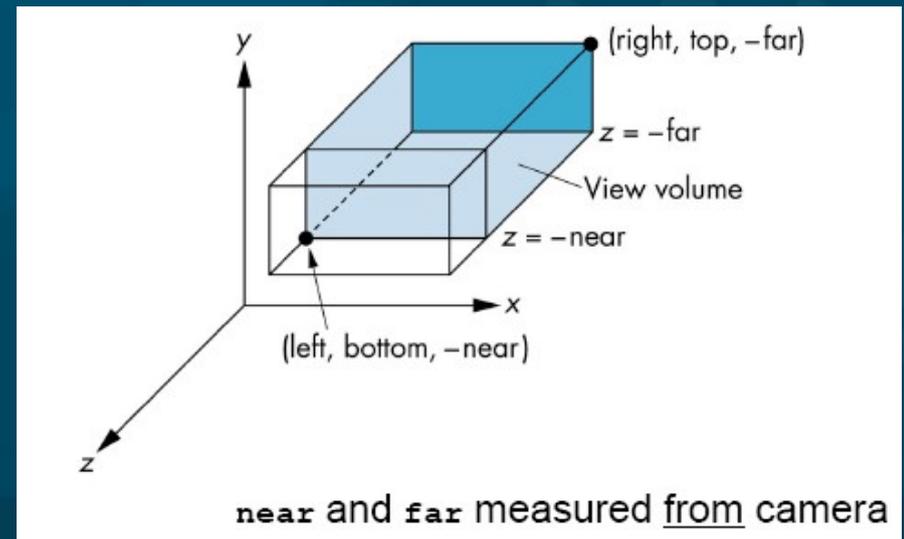
Orthographic projection

- The manual way:

- ◆ `glMatrixMode(GL_PROJECTION);`
- ◆ `glLoadIdentity();`
- ◆ `glMultMatrix(...);`

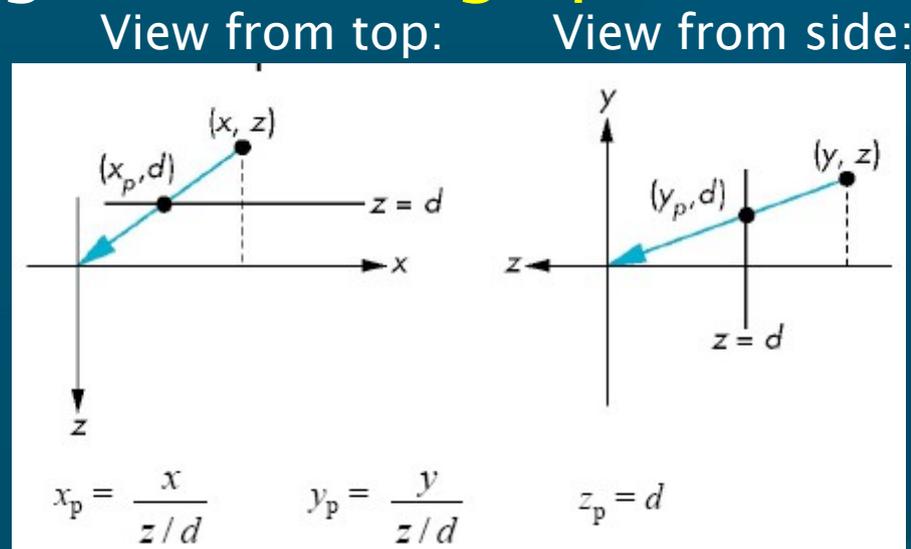
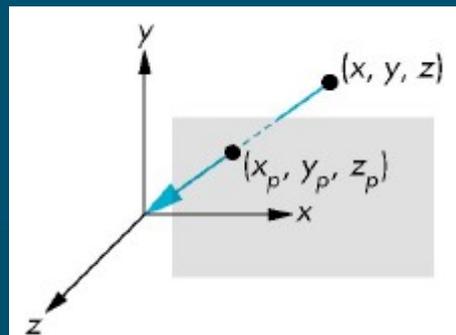
- The easier way with `glOrtho()`:

- ◆ `glMatrixMode(GL_PROJECTION);`
- ◆ `glLoadIdentity();`
- ◆ `glOrtho(left, right, bottom, top, near, far);`



Perspective projection

- Consider a **perspective** projection with center of projection (**CoP**) at origin, and **image plane** at $z=d$:



- A point $p = (x, y, z)$ projects to $q = (x_p, y_p, z_p = d)$

via

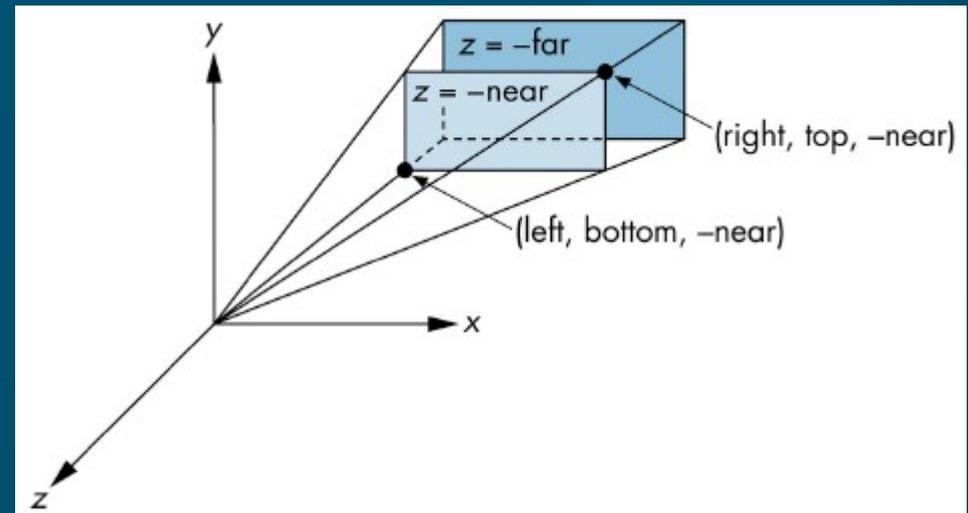
$$q = Mp, \text{ where } M = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{pmatrix}$$

Specifying perspective projection

- Can also do this manually with `glmMultMatrix()`

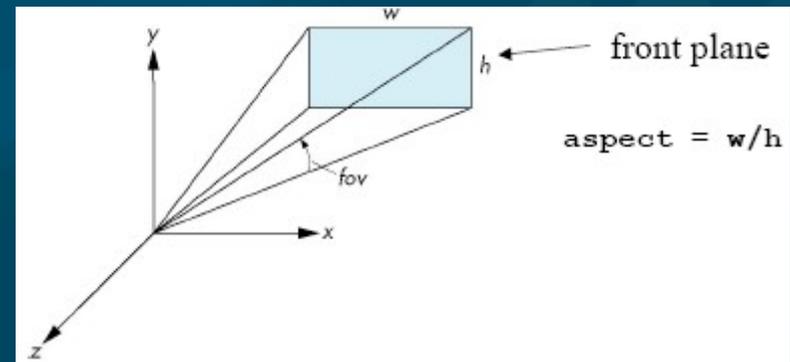
- Or use `glFrustum()`:

- ◆ `glFrustum(left, right, bottom, top, near, far)`



- Or use `gluPerspective()`:

- ◆ `gluPerspective(fov, aspect, near, far);`



- Easier to use than `glFrustum()`

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TODO

- Lab4: due next week Thu 15Mar
 - Add a virtual trackball using quaternions