

# Intro to POSIX Threads with FLTK

See:

- [FlChat/ example code](#)

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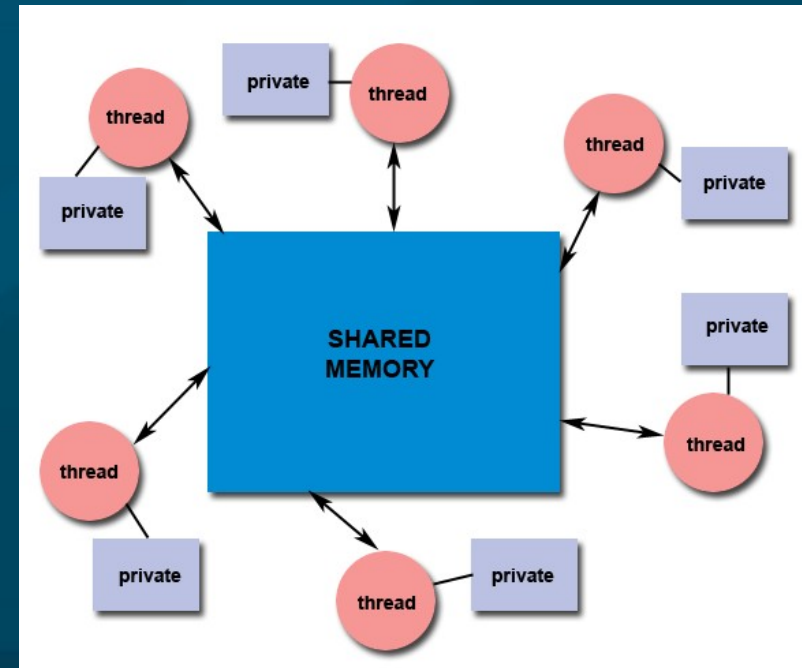
CMPT166

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# Threads and parallelism

- Threads are lightweight processes
- Threads allow concurrency
  - Make use of multiple processors
  - But still useful even on uniprocessor
- Threads use shared memory
  - Synchronization issues for shared objects
    - ◆ Thread-safe code?
  - May also have local (private) variables

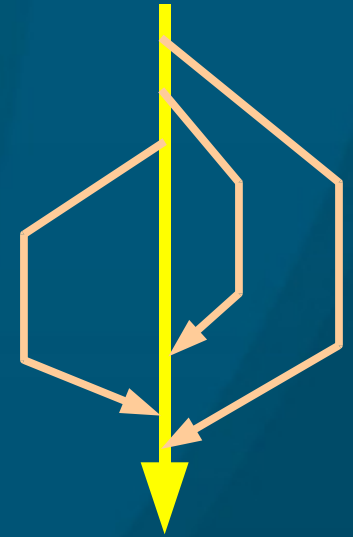


# Parallel program models

- How to **divide** work amongst threads?
- **Master/worker**:  
master thread **assigns** work to worker threads
  - Master typically handles **UI, input**
  - Static or dynamic **worker pool**
- **Coworkers**: all threads are **peers**:
  - Main thread participates in doing work
- **Pipeline**: each thread works on a different part of the task: e.g., automobile **assembly line**
  - **Function** parallelism vs. **data** parallelism

# Threads model: PThreads

- POSIX threading: **fork/join** model
- Start with **parent** thread (main program)
- Create **child** thread(s):
  - Specify a **callback** for the child to execute
  - Optional **parameter** to callback: **(void\*)**
  - **Shared memory** access to same data
  - Children may send **messages** to parent
    - ◆ May trigger parent to execute a callback
  - Child threads **exit** when callback finished



# PThreads API

- `pthread_create()`:
  - Parent calls this to **start** new child
  - Specify **start function** for child to run
- `pthread_exit()`:
  - Signals this thread is **done**
  - Implicit at **end** of child's start function
- `pthread_join()`:
  - Parent calls to **wait** for result from a child
- `pthread_self()`: returns my **thread ID** (`pthread_t`)

# PThreads: get results from child

- Thread **callbacks** are subroutines declared to return **void\*** and take one **void\*** parameter
  - ◆ `void* workerThread(void* d) { ... }`
- Parent may pass any user data **to child** via the **void\*** parameter
- Child may pass user data **back to parent** via the **void\*** return value
- Parent calls `pthread_join()` to **wait** for child to finish and **fetch** child's returned data

# PThreads vs Windows threads

- PThreads (POSIX threads) are a standard:
  - ◆ `#include <pthread.h>`
- But Windows has its own threading library:
  - ◆ `#include <process.h>`
- FLTK provides a small wrapper around both:
  - ◆ `#include "fl_threads.h"`
  - ◆ `fl_create_thread( tid, callback, userdata );`
  - FL\_Thread `tid` lets parent track child
  - `callback` is function for child to execute
  - `userdata` (optional) is passed to callback

# Issues with threads: locking

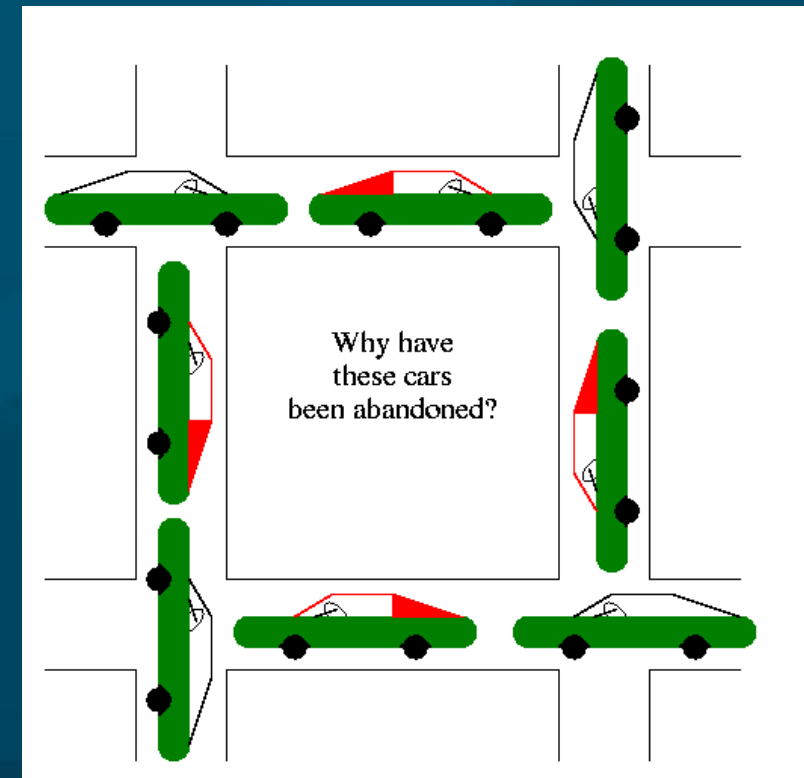
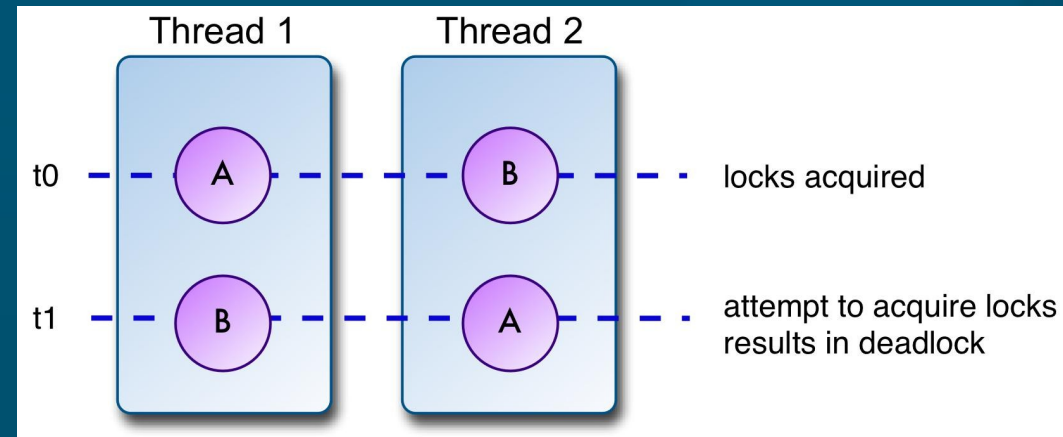
- Big problem whenever we have **concurrent** threads accessing **shared** data: data **corruption**
  - e.g., threads == **children** playing; shared resources == **toys/blocks**
- **Mutual exclusion** (mutex): only **one** thread accesses shared object at a time
- **Locks**: a way to implement mutex
  - ◆ Thread **asks** for lock before modifying object
  - ◆ If it **gets** the lock, it can modify
  - ◆ If not, **wait** (block) until the lock is freed
  - ◆ **Free** the lock when done modifying





# Problem with locks: deadlock

- Shared resources A, B each have own lock
- Thread 1 locks A, then asks to lock B
- Thread 2 locks B, then asks to lock A
- → both threads hang forever! Deadlocked
- → be careful with locks; only hold lock for minimum time needed



# Locking in FLTK

- FLTK provides one **global lock** so that multiple threads won't change the GUI simultaneously
- First call `Fl::lock()` in `main()` to **enable** threads
- Then before a thread modifies any **shared** object:
  - ◆ `Fl::lock();`
  - ◆ `myWindow->show(); // or other shared`
  - ◆ `Fl::unlock();`
- See FLTK doc ch10.

# When to use `Fl::lock()`

- Before a **shared resource** is modified
  - e.g., both parent and child want to **write** to a string buffer
- Before any FLTK **windowing** operation
  - `show()/hide()`
  - **timers** (`fl_add_timeout()`)
  - changing window **decorations**
  - In general, only the **parent** thread should do these

# Fl::awake()

- Children can send **messages** to the parent:
  - ◆ `void* msgToParent;`
  - ◆ `Fl::awake( msgToParent );`
- Parent (doing main FL event loop) **checks** for messages with
  - ◆ `void* msgFrChild = Fl::thread_message();`
- Message may be pointer to **any object (void\*)**
- Child may also ask parent to **run a callback**:
  - ◆ `void* runMe( void* u ) { ... }`
  - ◆ `Fl::awake( runMe, userdata );`

# Example code: FIChat

- Each of **client** and **server** has its own **UI** and **main** class: **Client**, **ClientUI**, **Server**, **ServerUI**
- **ServerUI**: creates **Server** object and initializes
  - Splits off a **thread** to wait and **listen**
- **ClientUI**: creates **Client** object
  - Upon connect, splits **thread** to **receive**
- This is still a **serial** server:
  - Can't handle multiple **simultaneous** clients
  - Extension: use threads to do **switchboard**