

Phong Shading and Texture Mapping

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CMPT370

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What's on for today

- Shading polygons
 - Flat shading
 - Gouraud shading
 - Phong shading
- Texture mapping
 - Coordinate transforms
 - Cylinder, sphere, cube maps
 - Bump mapping
 - Environment mapping

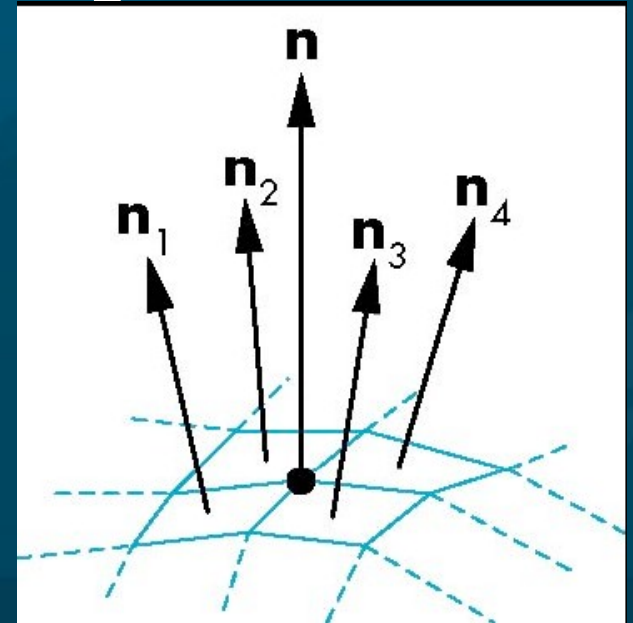
Shading polygons

- We specify in our model for each **vertex**:
 - Vertex **coordinates**
 - Vertex **colours**
 - Vertex **normal**
- Use lighting model to calculate vertex **shades**
- Smooth shading: vertex shades are **interpolated** across the polygon
 - ◆ `glShadeModel(GL_SMOOTH);`
- Flat-shading uses the colour of the **first** vertex:
 - ◆ `glShadeModel(GL_FLAT);`



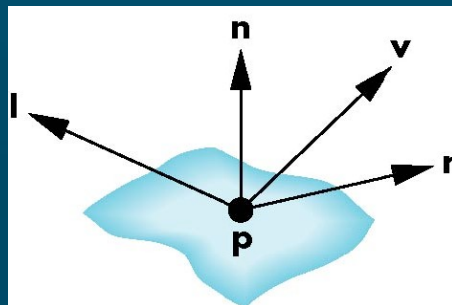
Calculating vertex normals

- Each polygon is **flat**: we can find **normal** vector
- One strategy: **average** the normals of the faces surrounding that vertex
- For **triangular** faces ABC: $AB \times AC$ gives **normal**
 - Magnitude is **area** of parallelogram
- **Sum** these cross-products:
 - Get a **weighted average** of face normals
 - Weighted by **area**

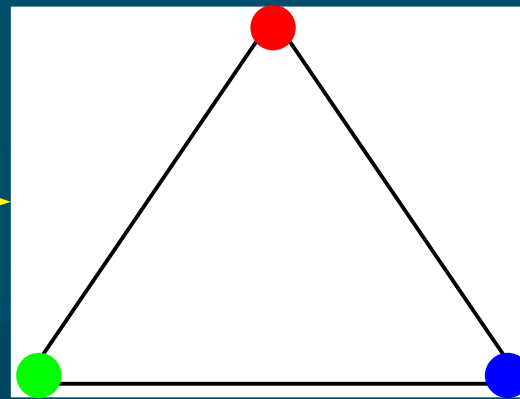


Gouraud shading

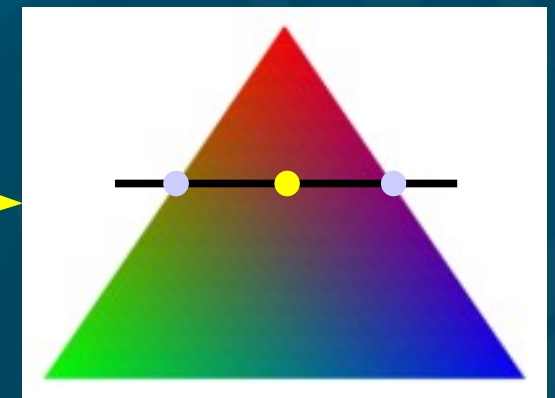
- Specify **vertex normals**
- Apply lighting model (ambient, diffuse, specular) to each vertex to get **vertex shades**
- **Interpolate** vertex shades across polygon
 - Interpolate along **edges** first
 - Then along each **scan line** (done in hardware)



vertex normals



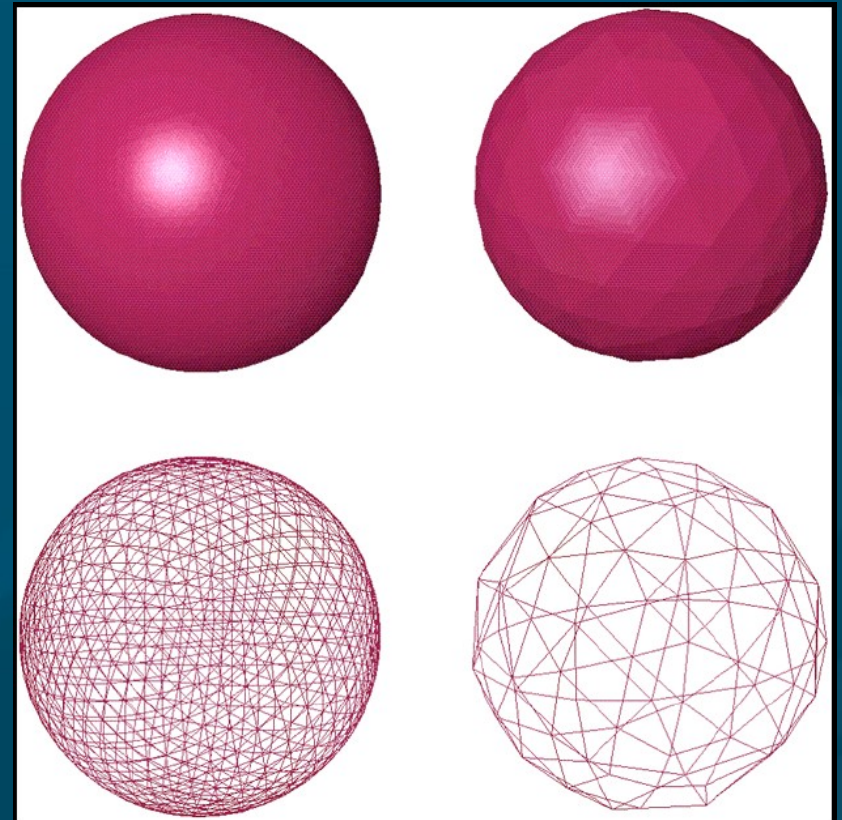
vertex shades



filled fragment

Gouraud shading: quality

- Depends on how **big** each polygon appears on **screen**, compared to **pixel** size
 - **Fewer** polygons => **bigger** on screen => **worse** quality



Phong shading

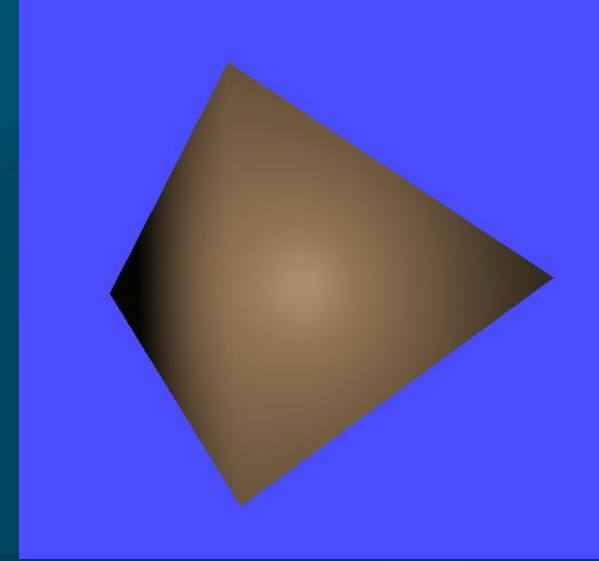
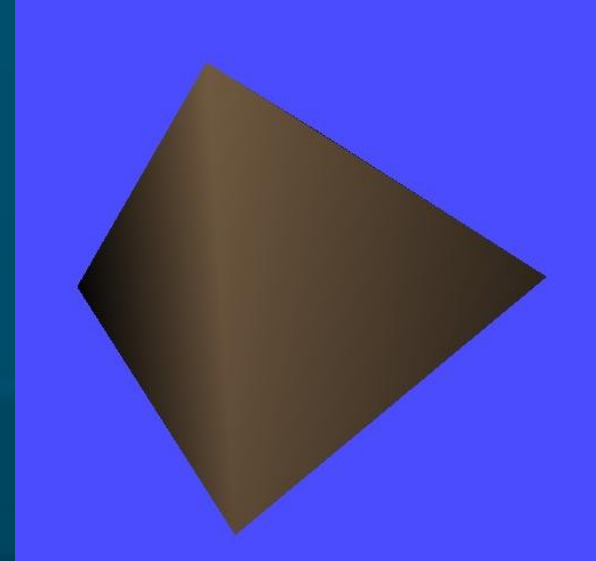
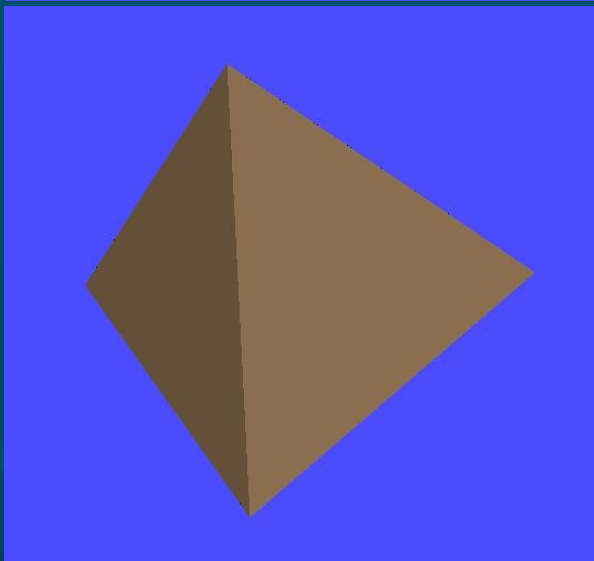
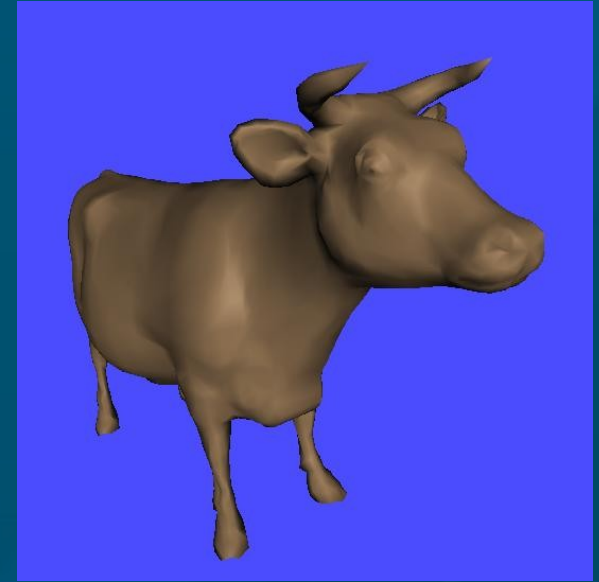
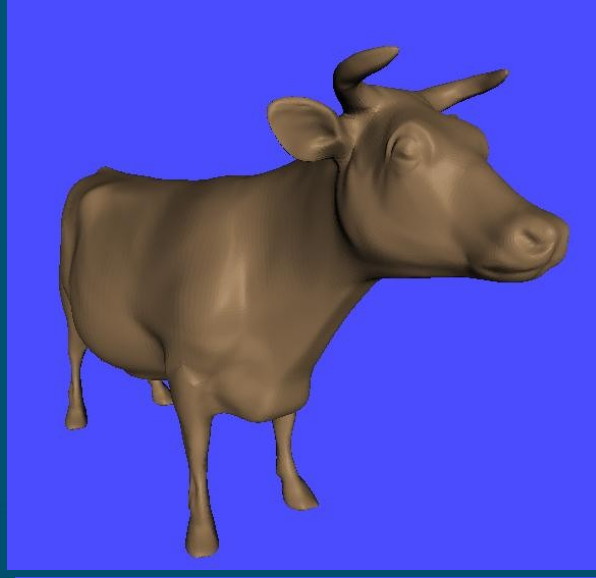
- Specify **vertex normals**
- **Interpolate** vertex **normals** across polygon
 - ◆ Interpolating **vectors**, not **intensities**!
- Apply lighting model at each **pixel** to get shades



- Gouraud may miss small specular **highlights**
- **OpenGL** implements Gouraud but not Phong
 - **Work** to calculate lighting model at each pixel

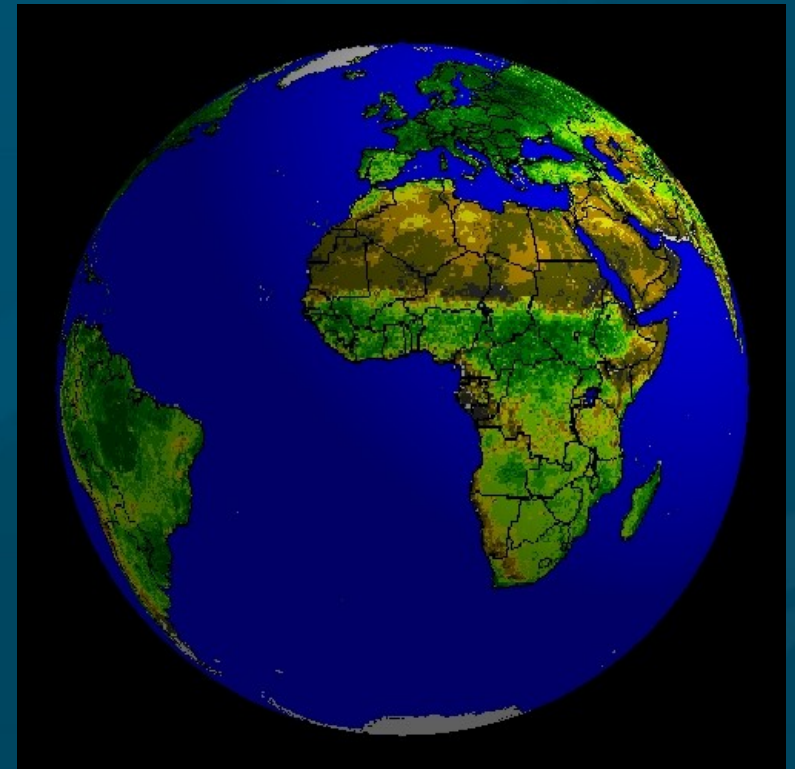
◆ Or use **programmable shaders!**

Flat vs. Gouraud vs. Phong



Texture mapping

- Complex **objects** with many varying shades:
 - Could use a new **polygon** for every shade
 - Or use an **image** pasted on top of the surface
- E.g., modeling the **earth**:
 - Blue **sphere** is too simple
 - Modeling every **continent** and **mountain** range with little polygons is too much
 - **Texture-map** a picture onto the sphere



Bump mapping

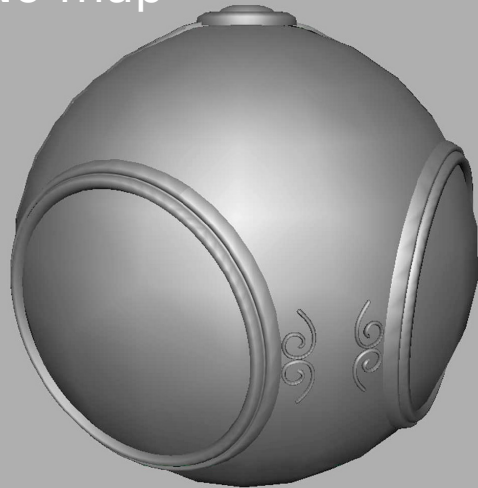
- e.g., modeling an orange:
 - Geometry is just a simple sphere
 - Texture map colours, striations, etc.
 - But surface is still smooth: what about small dimples?
 - ◆ Shading should change as light and view directions change
- Bump mapping tweaks the normal vectors to simulate dimples or bumpiness
 - Silhouette still reflects underlying geometry

Kinds of maps

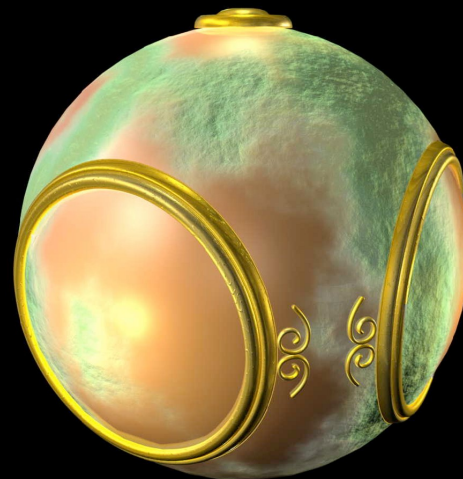
- **Texture** map:
 - Paste an **image** onto a surface
- **Bump** map:
 - Perturbs **normal** vectors in lighting model to simulate small changes in surface orientation
- **Environment** (reflection) map:
 - Use a picture of the surrounding **room/sky** for a texture map
 - Simulates **reflections** in very specular surfaces
- Only texture maps are built-in to OpenGL

Texture/bump/environ maps

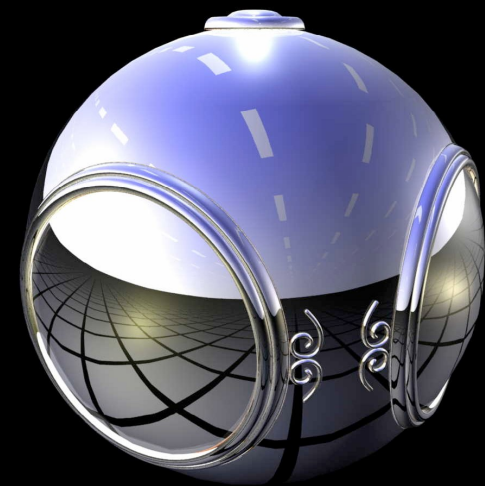
No map



Texture map



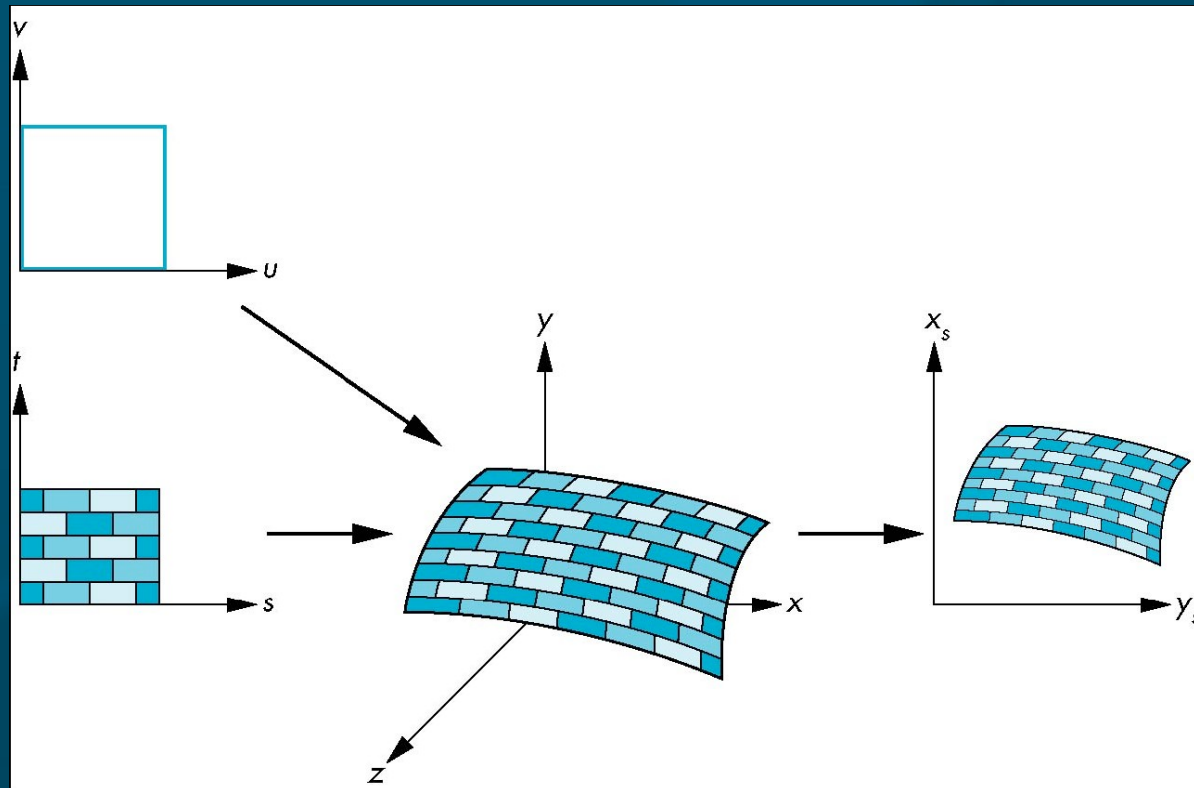
Bump map



Environment map

Mapping: coordinate systems

- Essential question for maps: how to map coordinate systems?
 - Parametric coords (u,v) describing the surface
 - Texture coords (s,t)
 - World coords (x,y,z)
 - Window coords (x_s, y_t)



Backward mapping

- For each point (x,y,z) on the **surface** in world coords, we want to go **backwards** to find which pixel (s,t) in the **texture** we should paste:
 - ◆ $s = s(x,y,z);$
 - ◆ $t = t(x,y,z);$
- **Two-part** mapping:
 - First map texture onto a simple **intermediate** shape
 - ◆ Cylinder
 - ◆ Sphere
 - ◆ Cube

Cylindrical mapping

- Parametric cylinder:

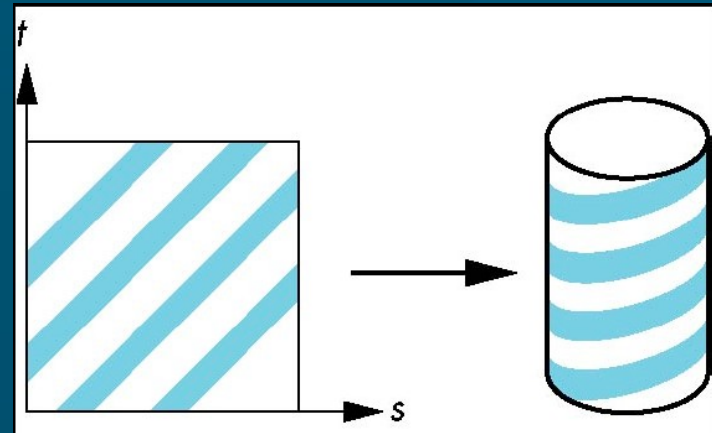
- ◆ $x = r \cos(2\pi s)$

- ◆ $y = r \sin(2\pi s)$

- ◆ $z = t/h$

- Map from

- Square $[0,1] \times [0,1]$ in (s,t) texture space to
 - Cylinder of radius r , height h in (x,y,z) world coordinates



Spherical maps, cube maps

- Parametric sphere:

- ◆ $x = r \cos(2\pi s)$

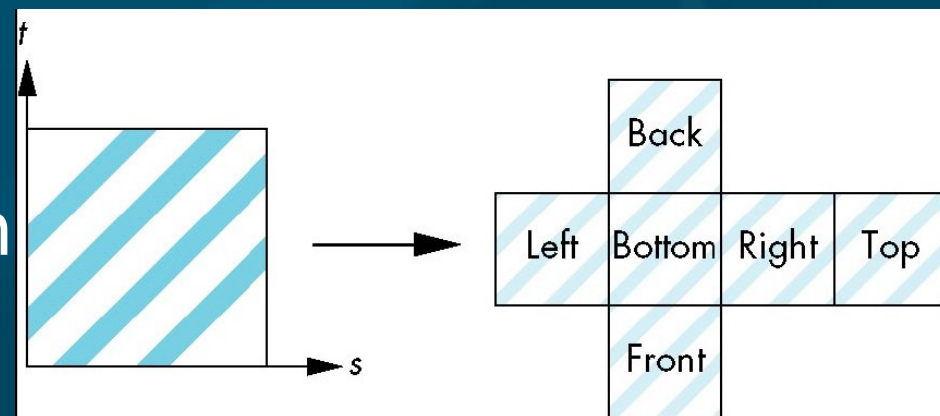
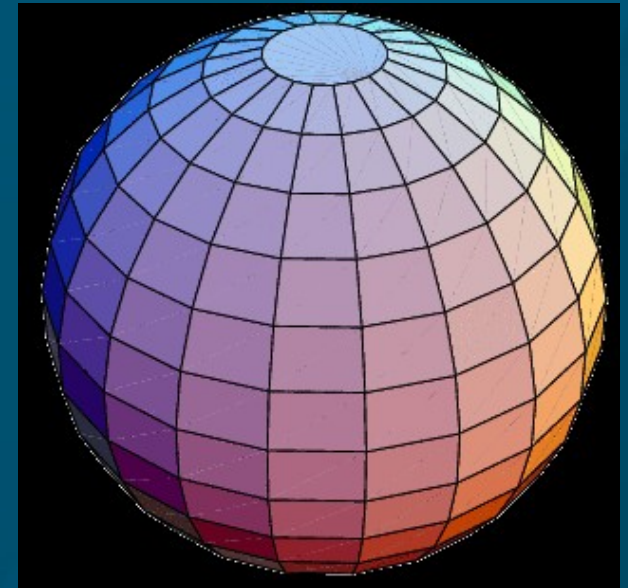
- ◆ $y = r \sin(2\pi s) \cos(2\pi t)$

- ◆ $z = r \sin(2\pi s) \sin(2\pi t)$

- Bad distortions at the poles

- Cube/box mapping:

- Easy with orthographic projection



- Both are widely used for environment maps

Implementing bump mapping



■ Parameterized surface:

- ◆ $p(u,v) = (x(u,v), y(u,v), z(u,v))$

- Tangent vectors: $p_u = \partial p / \partial u$, $p_v = \partial p / \partial v$

- Normal vector: $n = p_u \times p_v$

■ Perturbed surface: $p'(u,v) = p(u,v) + d(u,v) n(u,v)$

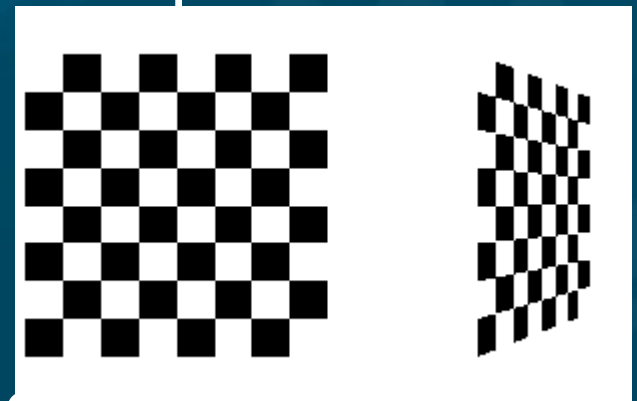
- $d(u,v)$ is the displacement function/map

■ Perturbed normal: $n' = p'_u \times p'_v$

- $n' \approx \left(\frac{\partial d}{\partial u} \right) (n \times p_v) + \left(\frac{\partial d}{\partial v} \right) (n \times p_u)$

Texture mapping in OpenGL

- **Bump** mapping / **environment** mapping are not provided in OpenGL
 - Can be done with **fragment** programs (GLSL)
- Using **texture** mapping in OpenGL:
 - **Create** texture and bind to object
 - Select how texture will **affect** each pixel
 - **Enable** texture mapping
 - Draw object, specifying texture **coordinates**
- See Redbook examples, checker.c



Creating a texture

- The following steps should be done once during **initialization**, not on every display refresh:
 - Read in an **image**: 3D array (rows, cols, RGBA)
 - Programmatically **generate** (`checker.c`), or
 - Read from **file** (`FI_JPEG_Image->data()`)
 - Bind new **texture object**: `glBindTexture()`
 - Specify **parameters**: wrapping, filtering
 - Load image data to **texture**: `glTexImage2D()`

Texture objects (OpenGL 1.1)

- Akin to display lists, but for textures
- Allows us to **reuse** textures, bind to objects
 - Request a new texture object **id**
 - ◆ `glGenTextures(1, &texName);`
 - Can also request **several** texture object ids
 - **Bind** this new texture object
 - ◆ `glBindTexture(GL_TEXTURE_2D, texName);`
- All subsequent texture **commands** are stored in this texture object
- Use `glBindTexture()` to **switch** texture objects

Loading image data to a texture

- `glTexImage2D(GL_TEXTURE_2D, level, intFmt, width, height, 0, format, type, pixels)`
- **level**: mip-mapping level, usually 0
- **intFmt**: `GL_RGB`, `GL_RGBA`, etc.
- **width, height**: must be power of 2, ≥ 64
 - ◆ (*border*: most hardware only supports '0')
- **format, type**: describe incoming pixels:
 - ◆ e.g., `GL_RGB`, `GL_UNSIGNED_BYTE`
 - ◆ Affected by `glPixelStore()`, similar to `glDrawPixels()`
- **pixels**: pointer to the actual image data

Texture size must be 2^n

- OpenGL requires the **width** and **height** of textures to be **powers of 2**
 - But need not be square
- GLU provides a helper function to **scale**:
 - ◆ `gluScaleImage(`
fmtIn, wIn, hIn, typeIn, *pixelsIn,
wOut, hOut, typeOut, *pixelsOut)

