

CMPT 231: Data Structures and Algorithms

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CMPT231

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Outline for today

- Administrivia
- Algorithms and asymptotic complexity
 - Example: Insertion sort
 - ◆ Notation: Θ , O , Ω , o , ω
- Divide-and-conquer
 - Example: Merge sort
 - ◆ Recursion and recurrence relations
 - Example: Maximum-subarray
 - Example: Matrix multiply
 - ◆ Naive method, divide-and-conquer method
 - ◆ Strassen's method

What is an algorithm?

- Well-defined **process** for solving a **problem**
 - Input → **Computation** → Output
- May be **expressed** in any appropriate language
 - **Pseudocode**, English, etc.
- May be **implemented** in many programming languages
 - **Python**, C, Java, etc.
- **Computing science** is not about **toolkits** (Python, C++, Java, etc.) but about **problem solving**

Algorithmic complexity

- Number of machine **instructions** needed to **execute** the algorithm
 - Expressed as a function of **size** of input
 - **Constant** factors are not important
- Depends on machine **architecture**
 - e.g., **GPUs** can perform many parallel operations very quickly
 - We'll ignore this in our machine model
- “**Running time**” (speed) is a more complex topic than just algorithmic complexity
 - Cache/**memory** hierarchy plays a big role

Basic machine model

- The basic **instruction set** we assume roughly follows most CPU architectures:
 - **Arithmetic**: $+$ $-$ $*$ $/$, $<$ $>$ \neq , left/right bitwise **shift**
 - **Data**: **load** (read), **store** (assign), **copy**
 - **Control**: **if/else**, **for/while**, functions
 - **Types**: **char**, **int**, **float** (with fixed word size)
 - ◆ Not **arbitrarily** large numbers
 - Basic data **structures**: **pointers**, fixed-length **arrays** (*not* Python lists / STL vectors)
- Each of these basic instructions is assumed to take **constant** execution time

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Example task: sorting

- Input: **array** of key-value pairs
 - wlog, let **keys** be the integers $1 \dots n$
 - **values** (payload) can be any data, staying attached to respective keys
- Output: array with elements **sorted** in increasing order by key
 - **In-place**: modify **original** array
 - **Out-of-place**: return a sorted **copy**
 - ◆ We'll focus on in-place sorting for now
- Standard fun: Python **sort/ed()**, C++/Java **sort()**
 - **How** do they do it?

Simple solution: insertion sort

- e.g., a hand of cards
- `insertion_sort(A, n):`

for $j = 2$ to n :

$key = A[j]$

$i = j - 1$

 while $i > 0$ and $A[i] > key$: # scoot over items

$A[i + 1] = A[i]$

$i = i - 1$

$A[i + 1] = key$

- Loop **invariant**: $A[1 .. j-1]$ are in sorted order
 - Check: **before** loop, **during** loop, **after** loop

Input	5	2	4	6	1	3
j=3:	2	5	4	6	1	3
j=4:	2	4	5	6	1	3
j=5:	2	4	5	6	1	3
j=6:	1	2	4	5	6	3
Out:	1	2	3	4	5	6

Insertion sort: complexity

- Let $t_j = \#$ times the 'while' condition is checked
- insertion_sort(A, n):
 - for $j = 2$ to n : # cost $c_0 * n$ times
 - $key = A[j]$ # $c_1 * n - 1$
 - $i = j - 1$ # $c_2 * n - 1$
 - while $i > 0$ and $A[i] > key$: # $c_3 * \sum_2^n t_j$
 - $A[i + 1] = A[i]$ # $c_4 * \sum_2^n (t_j - 1)$
 - $i = i - 1$ # $c_5 * \sum_2^n (t_j - 1)$
 - $A[i + 1] = key$ # $c_6 * n - 1$
- Summation notation: $\sum_2^n t_j = t_2 + t_3 + \dots + t_n$

Insertion sort: worst-case

- **Best-case** is if input is already sorted:
 - Still need to scan through, but all $t_j = 1$
 - → **Linear** in n : can express total complexity as $T(n) = a*n + b$, for some constants a, b
- **Worst case?** Input in reverse-sorted order!
 - 'while' loop is always max length: $t_j = j$
 - e.g., line 5: $c4 * \sum_2^n (t_j - 1) = c4 * \sum_2^n (j - 1)$
 $= c4 * (n - 1)(n)/2 = (c4 / 2) * n^2 - (1/2) * n$
 - ◆ Similarly for the other lines in the function
 - → **Quadratic** in n
- **Average** case: random order: $t_j = j/2$, quadratic

$\Theta()$ notation

- The **constants** c_1, c_2, \dots may vary on different platforms, but as n gets big, constants irrelevant
 - Even the n term gets dominated by n^2
- Insertion sort has complexity on the **order** of n^2
 - Notation: $T(n) = \Theta(n^2)$ (“big theta”)
- $\Theta(1)$ means the algorithm runs in **constant time**

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Divide and conquer

- Insertion sort is **incremental**:
 - At each step, given that $A[1 \dots j-1]$ is sorted, insert $A[j]$ such that $A[1 \dots j]$ is sorted
- Another **design** strategy:
 - **Split** up the task into smaller **chunks**
 - When chunks are **small** enough, solve **directly** (base case)
 - **Combine** results and return up the stack
- Can implement via function **recursion** or **loops**
- **Merge sort** is an example, which ends up being more efficient than insertion sort

Divide and conquer: merge sort

■ In English:

- Split array in half
 - ◆ If array has only **one** element, we're done
- Recurse to sort each half
- Merge two sorted sub-arrays

■ In pseudocode:

```
merge_sort(A, p, r):
```

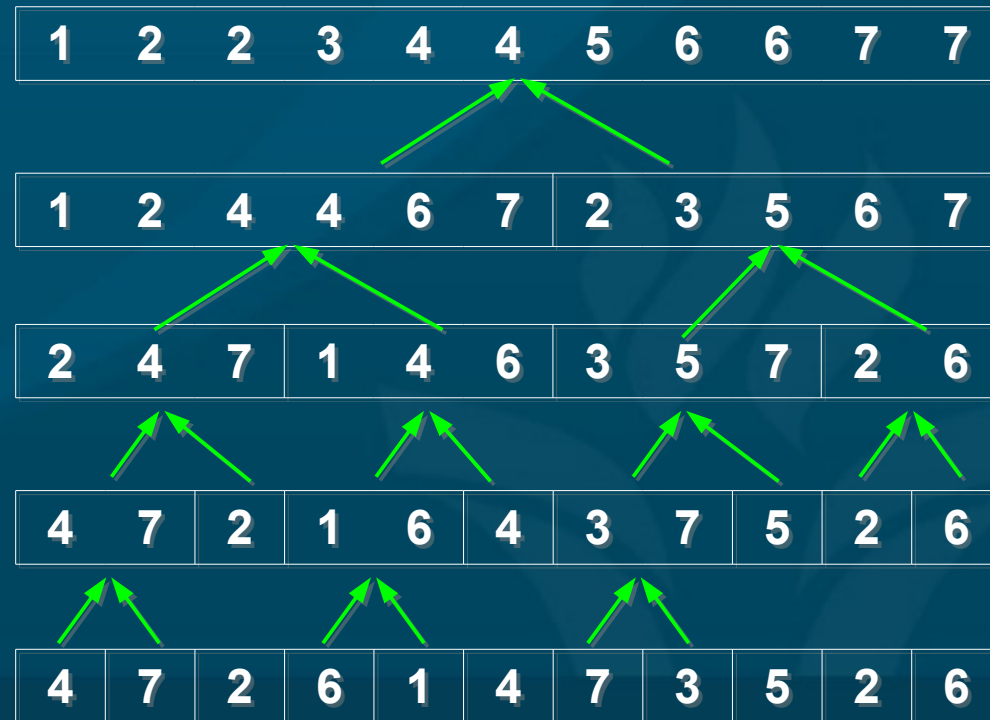
```
  if p < r:
```

```
    q = floor( (p + r) / 2 )
```

```
    merge_sort(A, p, q)
```

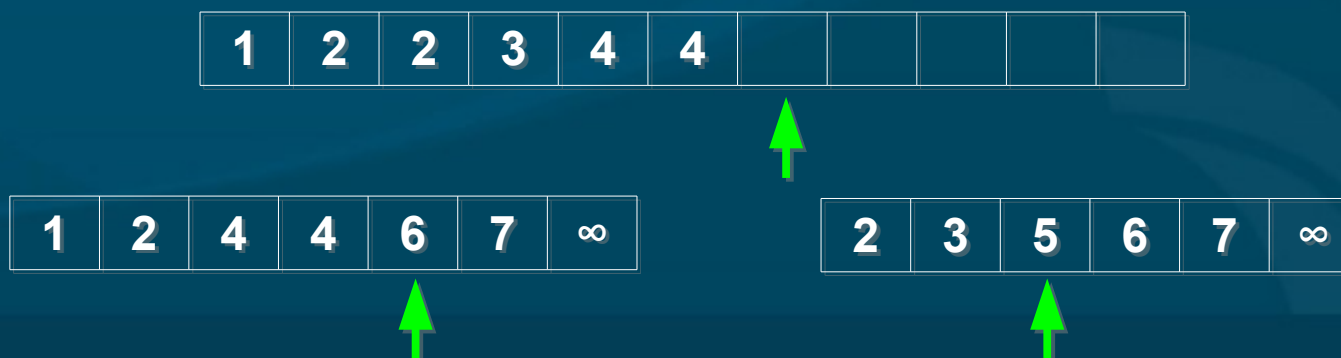
```
    merge_sort(A, q+1, r)
```

```
    merge(A, p, q, r)
```



Linear-time merge

- How to do the **merge**?
- $A[p .. q]$ and $A[q+1 .. r]$ are each **sorted**, $p \leq q < r$
- Make temp **copies** of each sub-array (left + right)
 - Append “**infinity**” item to end of each copy
- **Step** through both sub-array copies:
 - **Compare** first item from each sub-array
 - Copy **smaller** one into main array and move to **next** item in that list



Linear-time merge: pseudocode

■ merge(A, p, q, r):

(n1, n2) = (q - p + 1, r - q)

new arrays: L[1 .. n1+1], R[1 .. n2+1]

for i in 1 .. n1: L[i] = A[p + i - 1]

for j in 1 .. n2: R[j] = A[q + j]

(L[n1+1], R[n2+1]) = (∞, ∞)

(i, j) = (1, 1)

for k in p .. r:

if L[i] ≤ R[j]:

 A[k] = L[i]

 i = i + 1

else:

 A[k] = R[j]

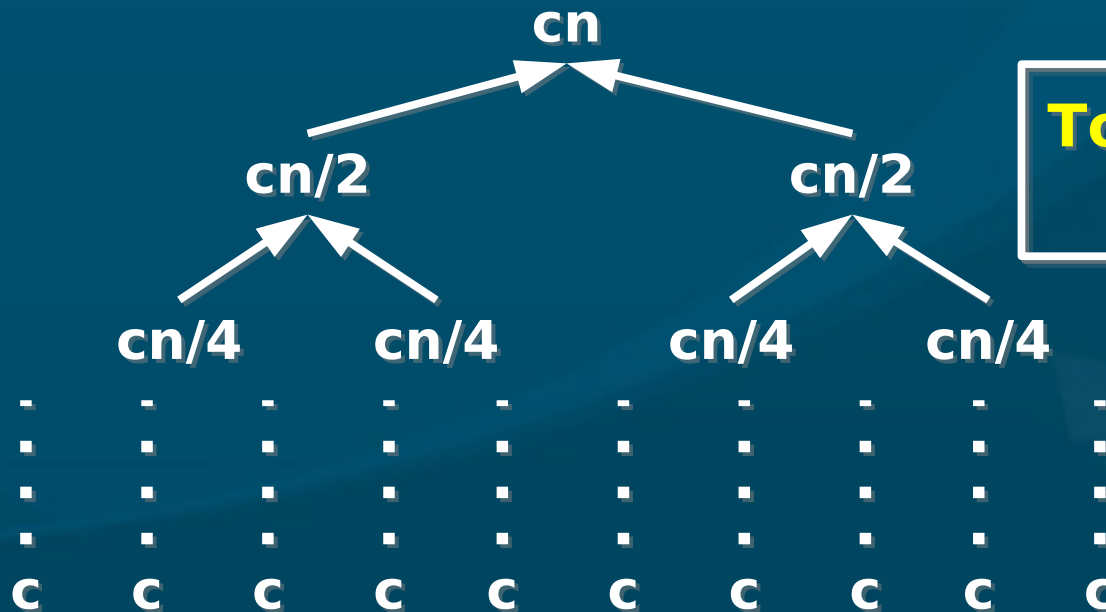
 j = j + 1

Complexity: $\Theta(n)$
where $n = r - p + 1$

Merge sort: complexity

- How to analyse **complexity** of a recursive algo?
- **Recurrence** relation: **base case** + **inductive step**
- **Base case**: if $n = 1$, then $T(n) = \Theta(1)$
- **Inductive step**: if $n > 1$, then $T(n) = 2 * T(n/2) + \Theta(n)$

↑
lg(n) levels
↓



Total complexity:
 $\Theta(n \lg(n))$

Asymptotic growth

- Behaviour “in the limit” (for big n)

- Def: $f(n) \in \Theta(g(n))$

iff \exists constants c_1, c_2, n_0 such that

$$0 \leq c_1 g(n) \leq f(n) \leq c_2 g(n)$$

for all $n > n_0$

- $\Theta(g(n))$ is a **set** of functions

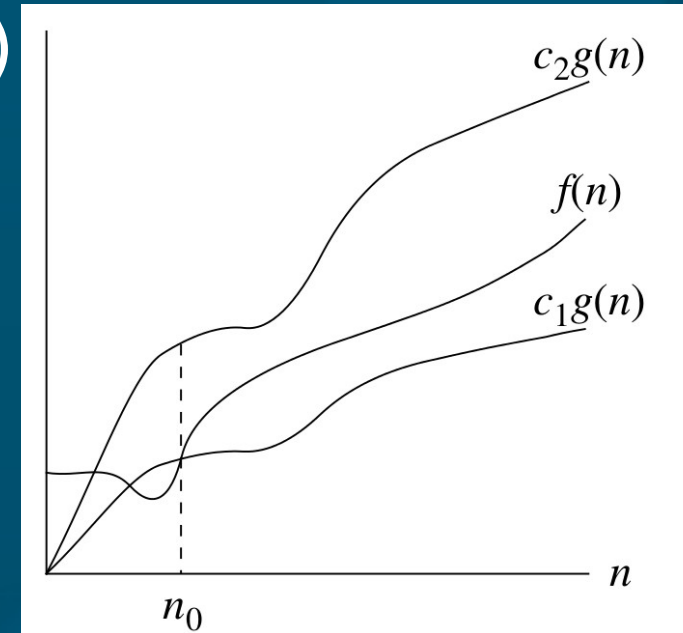
- $f(n)$ is “sandwiched” between $c_1 g(n)$ and $c_2 g(n)$

- “Big O”: $O(g(n))$ specifies an **upper-bound**

- e.g., $\Theta(n^2) \subset O(n^2) \subset O(n^3)$

- “Big Omega”: $\Omega(g(n))$ specifies a **lower-bound**

- Other examples?



Asymptotic short-hand

- When Θ et al. are used on the **right** side of $=$,
 - Means “there exists” $f \in \Theta(g)$
 - e.g., $2n^2 + 3n = \Theta(n^2)$
- When Θ et al. are used on the **left** side of $=$,
 - Means “for all” $f \in \Theta(g)$
 - e.g., $4n^2 + \Theta(n \lg(n)) = \Theta(n^2)$
(this holds true for any function in $\Theta(n \lg(n))$)

Asymptotic domination

- “Little o”: $f \in o(g)$ iff for all $c > 0$, there exists n_0 such that $0 \leq f(n) < cg(n)$ for all $n > n_0$.
 - i.e., as $n \rightarrow \infty$, $f(n) / g(n) \rightarrow 0$
- “Little omega”: $f \in \omega(g)$ iff for all $c > 0$, there exists n_0 such that $0 \leq cg(n) < f(n)$ for all $n > n_0$.
 - i.e., as $n \rightarrow \infty$, $f(n) / g(n) \rightarrow \infty$
- E.g.: $n^{1.9999} = o(n^2)$, $n^2 / \lg(n) = o(n^2)$,
but $n^2 / 100000 \neq o(n^2)$,
- $n^{2.000001} = \omega(n^2)$, $n^2 \lg(n) = \omega(n^2)$

Useful math identities

- All **logs** are the same up to a constant factor:
 - $\log_a(n) = \log_b(n) / \log_b(a)$
 - So we just use **lg** = \log_2 for convenience
- $\Theta(1) \subset o(\lg(n)) \subset o(n) \subset o(n^{p>1}) \subset o(p^n)$
- In fact, for all $a > 1$ and b : $n^b / a^n \rightarrow 0$ as $n \rightarrow \infty$.
 - Hence, $n^b = o(a^n)$
- $n! = n(n-1)(n-2)\dots(2)(1)$
Stirling's approximation:
 - hence **lg(n!) = $\Theta(n \lg(n))$**

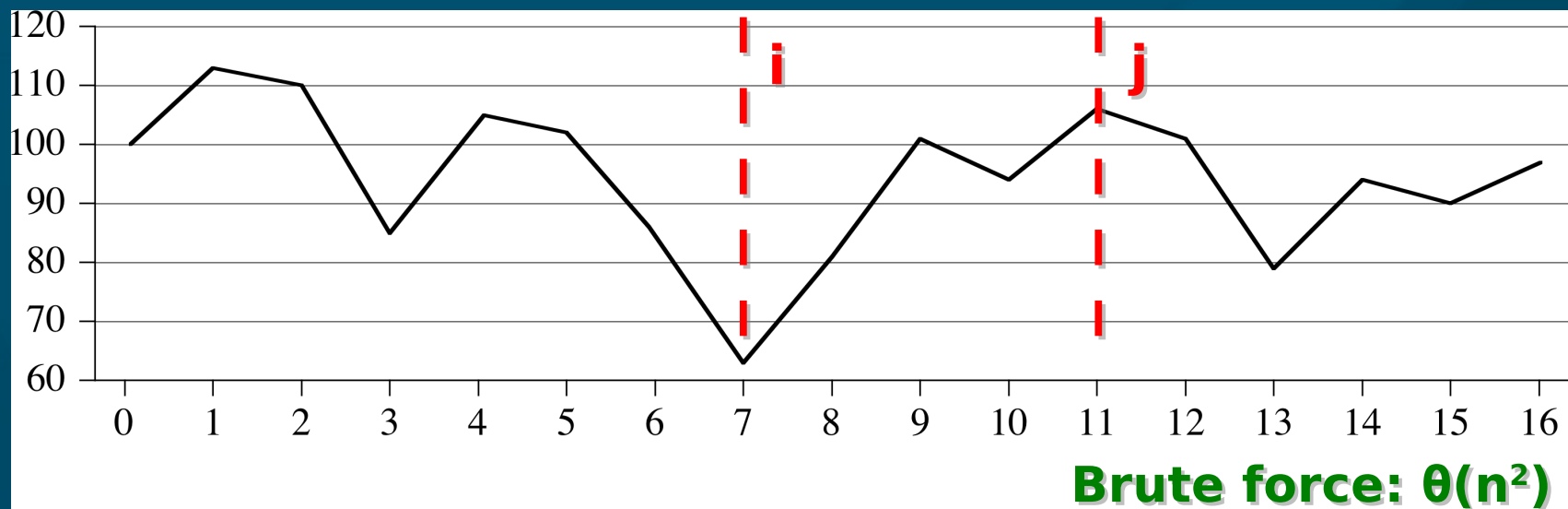
$$n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \left(1 + \Theta\left(\frac{1}{n}\right)\right),$$

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Maximum subarray

- A more complex example of **divide-and-conquer**
- **Input:** array $A[1..n]$ of numbers (some negative)
- **Output:** indices (i,j) that maximize $\text{sum}(A[i..j])$
 - e.g., daily change in **stock** price:
when was optimal time to **buy** (i) & **sell** (j)?



Day	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Price	100	113	110	85	105	102	86	63	81	101	94	106	101	79	94	90	97
Change		A[1] 13	-3	-25	20	-3	-16	-23	18	20	-7	12	-5	-22	15	-4	7

Max subarray: algorithm

- Divide-and-conquer can do it in $\theta(n \lg(n))$:
 - Split array in half
 - Recursively find max subarray in each half
 - ◆ (What's the base case?)
 - Find max subarray which spans the midpoint
 - Pick the best out of the 3 subarrays and return
- Finding max subarray spanning midpoint in $\theta(n)$:
 - Decrement i from mid down to low to maximize $\text{sum}(A[i .. mid])$
 - Increment j from $mid+1$ up to $high$ to maximize $\text{sum}(A[mid+1 .. j])$



Max subarray: complexity

- $\text{max_subarray}(A, \text{low}, \text{mid}, \text{high})$: $\rightarrow T(n)$
 - Split $\rightarrow \theta(1)$
 - Recurse on each half $\rightarrow 2T(n/2)$
 - Subarray spanning midpoint $\rightarrow \theta(n)$
 - Return best of 3 $\rightarrow \theta(1)$
- **Recurrence** relation:
 - Inductive step: $T(n) = 2T(n/2) + \theta(n)$
 - Base case: $T(1) = \theta(1)$
- Same recurrence as **merge sort**: $\theta(n \lg(n))$
- Actually, max subarray can be done in $\theta(n)$!
 - See exercise #4.1-5

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Example: matrix multiply

■ Input: two $n \times n$ matrices $A[i,j]$ and $B[i,j]$

■ Output: $n \times n$ matrix $C = A * B$:

- $C[i,j] = \sum_{k=1}^n (A[i,k] B[k,j])$

■ Simplest method:

for i in 1 .. n:

for j in 1 .. n:

for k in 1 .. n:

$C[i,j] += A[i,k] * B[k,j]$

- Complexity? Can we do better?

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \cdot \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

Basic divide-conquer algorithm

- **Divide-and-conquer**: split matrices into 4 parts:

- (assume n is a power of 2)

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \cdot \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

- **Recurse** 8 times to get products of sub-matrices
- Add and **combine** into result:

- $C_{11} = A_{11} * B_{11} + A_{12} * B_{21},$

- $C_{12} = A_{11} * B_{12} + A_{12} * B_{22},$

- $C_{21} = A_{21} * B_{11} + A_{22} * B_{21},$

- $C_{22} = A_{21} * B_{12} + A_{22} * B_{22}.$

- **Base case?**

- (Generalise to when n is not a power of 2?)

Basic div-conq: complexity

- **Split** of matrices can be **constant** time if done using indices rather than copying matrices
- Each **recursive** call takes $T(n/2)$; do **8** of them
- **Combining** results takes $\Theta(n^2)$ due to addition (each entry in $C[]$ requires one addition)
- \Rightarrow **Recurrence** relation: $T(n) = 8T(n/2) + \Theta(n^2)$
 - **Base case**: $T(1) = \Theta(1)$
- Doing **8** recursive calls kills us here; total complexity is still $\Theta(n^3)$, no better than brute-force
- If we can save even **1 recursive call**, even at the expense of $o(n^2)$ of work, it will help

Strassen's method

- Make 10 **sums** of submatrices:

$$S_2 = A_{11} + A_{12},$$

$$S_3 = A_{21} + A_{22},$$

$$S_1 = B_{12} - B_{22},$$

$$S_4 = B_{21} - B_{11},$$

$$S_5 = A_{11} + A_{22},$$

$$S_6 = B_{11} + B_{22},$$

$$S_7 = A_{12} - A_{22},$$

$$S_8 = B_{21} + B_{22},$$

$$S_9 = A_{11} - A_{21},$$

$$S_{10} = B_{11} + B_{12}.$$

- Recurse** 7 times to get 7 products:

$$P_2 = S_2 * B_{22},$$

$$P_3 = S_3 * B_{11},$$

$$P_1 = A_{11} * S_1,$$

$$P_4 = A_{22} * S_4,$$

$$P_5 = S_5 * S_6,$$

$$P_6 = S_7 * S_8,$$

$$P_7 = S_9 * S_{10}.$$

- Add** products and combine for result:

$$C_{11} = P_5 + P_4 - P_2 + P_6,$$

$$C_{12} = P_1 + P_2,$$

$$C_{21} = P_3 + P_4,$$

$$C_{22} = P_5 + P_1 - P_3 - P_7.$$

Strassen: complexity

- Even though **more** sums are done, they are all still $\Theta(n^2)$ and so don't change **asymptotic** cplxity
 - Although for **smaller** n it may not be worth it
- **Recurrence**: $T(n) = 7T(n/2) + \Theta(n^2)$
 - $T(1) = \Theta(1)$
- **Solution** to the recurrence is $T(n) = \Theta(n^{\lg 7})$
- In **general**, for $T(n) = a T(n/b) + \Theta(f(n))$:
 - if $f(n)$ is smaller than $O(n^{\log_b(a)})$:
 - ◆ Then $T(n) = \Theta(n^{\log_b(a)})$
 - ◆ **Leaves** dominate recursion tree
- One case of the “**master theorem**”